



Al to improve data quality for automating drilling reports

Surface logging data automated QC

2024/10/03 - SPE Aberdeen



About Me

Brief bio





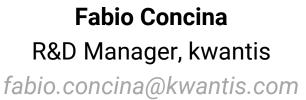
BSc in Mathematical Engineering



MSc in Statistics



In 2015 joined **kwantis** as a Software Engineer



In the last 9 years working on complex Software and Data Science problems

Now managing the R&D division

About kwantis

Innovative company with worldwide reach

Innovative company providing **Software** solutions and consulting to the Energy industry



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Our use case

Our use case: id3 Software

id3 provides **advanced analytics for drilling operations**, integrating HF and LF data for performance analysis and optimization



150+

Active drilling sites



3000+

Processed wells



35+

Countries



3B+

Records

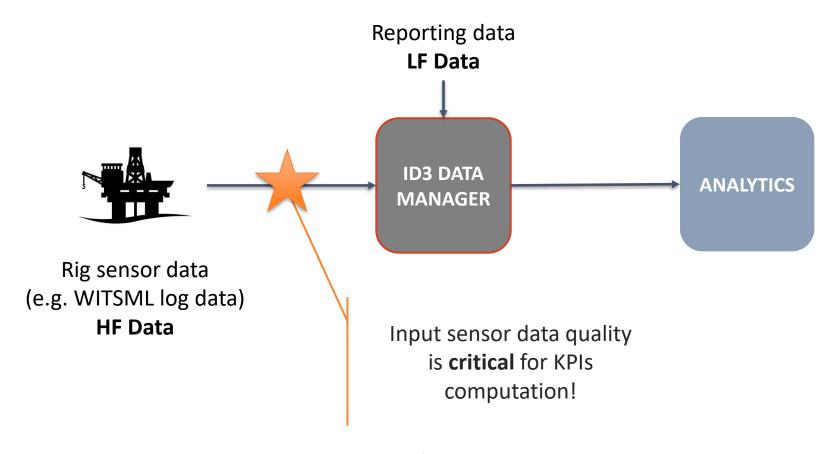


400+

KPIs

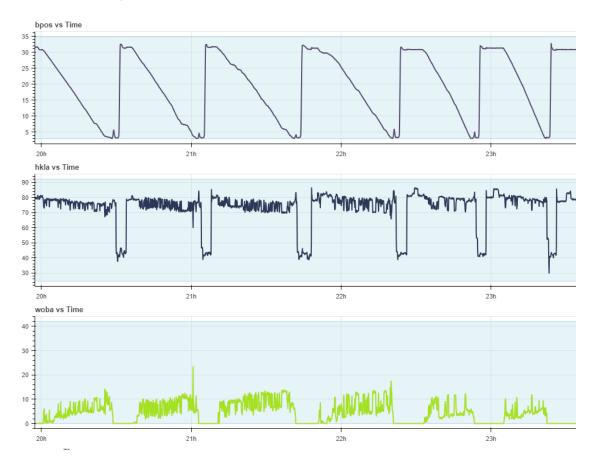


Input sensor data quality



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Sensor data example



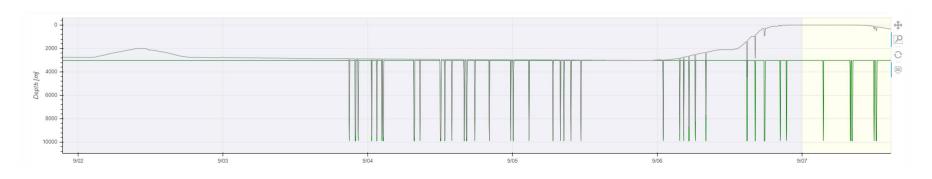
BLOCK POSITION

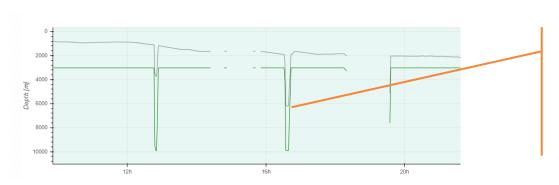
HOOK LOAD

WEIGHT ON BIT

Bad data quality

Examples of **bad** data quality



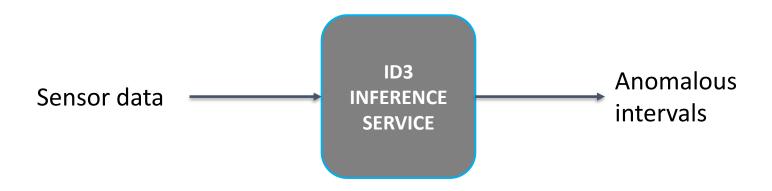


Spikes and **gaps** in depth data (Bit position and Hole depth)

Our solution

id3 Inference Service

Our solution has been to **build a new id3 service** integrating traditional anomaly detection techniques and AI models



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Our solution

2 Steps

Step 1

Step 2

Univariate Anomaly Detection

Detecting anomalies using prior **expert knowledge**, for example:

- Value range, or value change range
- Intervals with constant value measurements
- Association rules between variables

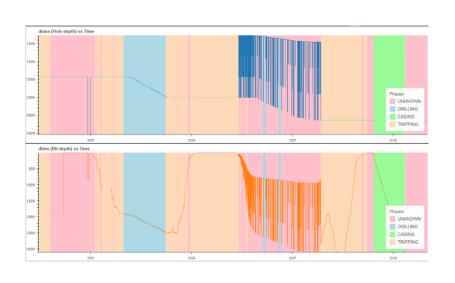
Multivariate Anomaly Detection

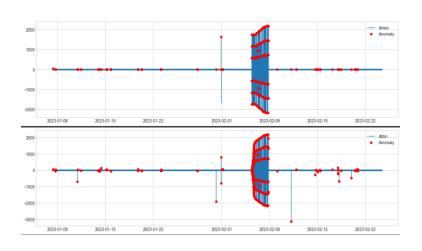
Al models considering several variables together. We are currently using an **autoencoder** architecture.

Step 1

Value range change

Example: value range change



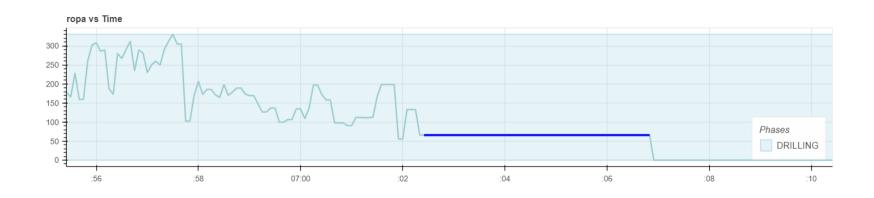


Depth data exhibits incorrect oscillating behavior which is physically impossible

Differentiating the signal allows an easy detection of the anomalies

Intervals with constant value measurements

Example: Intervals with constant value measurements



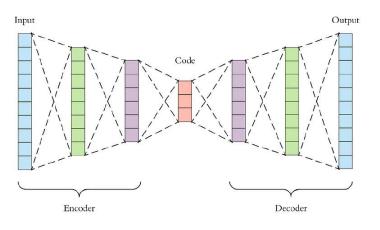
In this case the Rate of Penetration (ROP) remains suspiciously **flat for several minutes**.

For different measurements is almost impossible to have the same value over an extended period

Autoencoder architecture

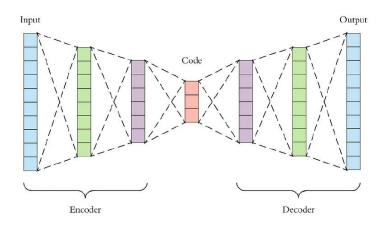
Step 2 introduces AI methods to detect **more complex** anomalies, for example patterns not consistent with a normal drilling activity

We use the **autoencoder** neural network architecture, which is a type of artificial neural network designed for dimensionality reduction and feature learning



Autoencoder architecture

The **input** to the network is a sliding window of the sensor data, e.g., 10 minutes



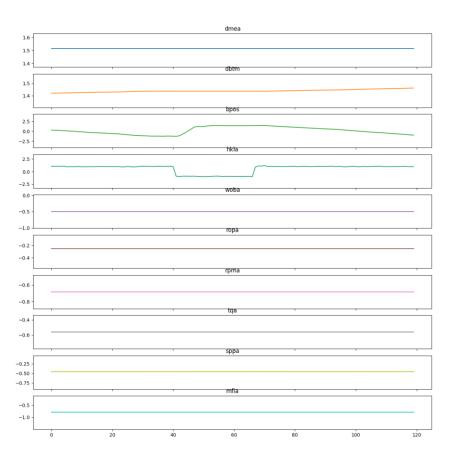
The **output** is again a window with the same size

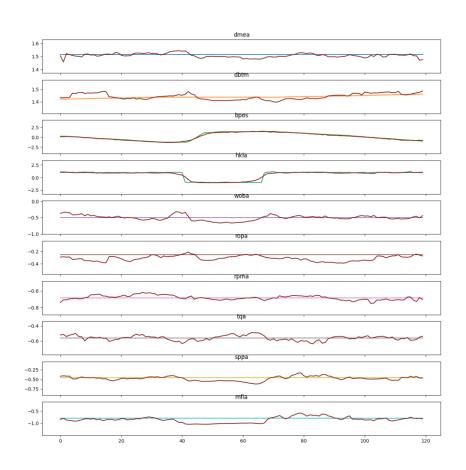
The layer in the **middle** "compresses" the information and acts a feature extractor

Multivariate AD

Step 2

Example input





Multivariate AD

Reconstruction error

We define the **reconstruction error** for each data point as the squared difference of that data point and its reconstruction:

Error
$$(x_{i,t}, \hat{x}_{i,t}) = (x_{i,t} - \hat{x}_{i,t})^2$$
,

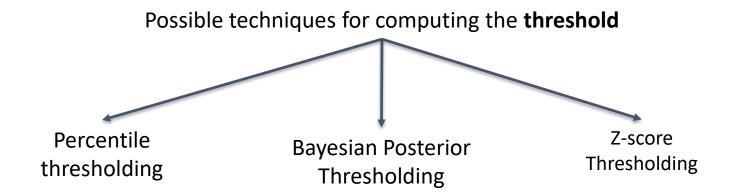
Thresholding system

The key idea is that normal signal is reconstructed with **low error**, whilst anomalous signal is reconstructed with **high error**

How can we say when error is **high**?

We need a threshold

Thresholding system



We devised and are using a *novel* thresholding technique based on class distribution, which requires labeled data

Step 2

Example of a complex anomaly

Example of complex anomaly detected

A drilling activity is ongoing, but during stand connection (when Hook Load drops) we have a **positive and high**Weight on Bit.

3 intervals are detected as anomalous



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Future Work

Several lines of improvement

What's next?

Currently training a bigger, more powerful AI model, with significantly more data

Transition to **density estimation** within the neural network architecture

Enhanced univariate anomaly detection procedures

Thank you